

	Type	L #	Hits	Search Text	DBs	Time Stamp	Comments
1	BRS	L2	292	pose and model and refin\$6 and motion and transform\$6	USPAT	2005/08/18 14:23	
2	BRS	L3	9	2 and (geometric\$3 near2 match\$3)	USPAT	2005/08/18 15:21	
3	BRS	L4	5	3 and (motion near3 transform\$6)	USPAT	2005/08/18 14:27	
4	BRS	L5	2	4 and tensor\$1	USPAT	2005/08/18 14:28	
5	BRS	L7	1	"6850646".pn.	USPAT	2005/08/18 14:28	
6	BRS	L8	1	7 and tensor\$1	USPAT	2005/08/18 14:28	
7	BRS	L6	954	"6850"	USPAT	2005/08/18 14:27	
8	BRS	L9	2	4 and (look\$3 near3 table\$1)	USPAT	2005/08/18 14:30	
9	BRS	L12	100344 2	(geometr\$5 or graph\$5 or line\$1 or topolog\$6 or structur\$3) same (compar\$6 or match\$3 or resembl\$5 or likelihood or correspondence\$1 or similar\$5)	USPAT	2005/08/18 15:02	
10	BRS	L13	229422	12 same (pose\$1 or posture or orientation or position\$3 or attitude)	USPAT	2005/08/18 15:04	

	Type	L #	Hits	Search Text	DBs	Time Stamp	Comments
11	BRS	L14	110551	((pose\$1 or posture or orientation or position\$3 or attitude) near\$3 (refin\$6 or smooth\$3 or true or correct\$3 or perfect))	USPAT	2005/08/18 15:05	
12	BRS	L15	22072	13 and 14	USPAT	2005/08/18 15:05	
13	BRS	L16	181	12 and (pose\$1 near\$5 (refine\$6 or true or correct or perfect))	USPAT	2005/08/18 15:06	
14	BRS	L17	83	16 and ((model\$1 or submodel\$1 or template\$1 or reference or prototype or database or stored or prestored) near\$5 (pattern\$1 or image\$1 or video or photo\$6 or picture\$1 or pixel\$1 or pel\$1))	USPAT	2005/08/18 15:21	
15	BRS	L18	69	17 and (boundar\$3 or edge\$3 or outline\$1)	USPAT	2005/08/18 15:08	
16	BRS	L19	5	18 and (motion near\$3 transform\$6)	USPAT	2005/08/18 15:17	
17	BRS	L20	65862	((pose or position\$3 or orientation or posture or attitude) near\$3 (refin\$6 or estimat\$4 or approximat\$4))	USPAT	2005/08/18 15:19	
18	BRS	L21	8178	20 same (boundar\$3 or edge\$3)	USPAT	2005/08/18 15:19	

	Type	L #	Hits	Search Text	DBs	Time Stamp	Comments
19	BRS	L22	671	21 same (video or image\$1 or picture\$1 or photo\$6 or pel\$1 or pixel\$1)	USPAT	2005/08/18 15:20	
20	BRS	L23	473	22 and ((model\$1 or submodel\$1 or template\$1 or reference or prototype or database or stored or prestored or known) near5 (pattern\$1 or image\$1 or video or photo\$6 or picture\$1 or pixel\$1 or pel\$1))	USPAT	2005/08/18 15:21	
21	BRS	L24	97	23 and ((graph\$7 or geometric\$3 or line\$1 or topolog\$4 or structur\$2) near3 (similar\$4 or correspondence or resembl\$4 or match\$3))	USPAT	2005/08/18 15:23	
22	BRS	L25	2	24 and (motion near2 transform\$6)	USPAT	2005/08/18 15:24	
23	BRS	L26	227	(pose near3 (estimat\$4 or approxim\$4 or perfect or clear or true or refin\$6))	USPAT	2005/08/18 15:29	
24	BRS	L27	423	((true or initial or start\$3 or begin\$4 or refin\$6) near3 pose\$1)	USPAT	2005/08/18 16:14	
25	BRS	L28	47	27 same (match\$3 or similar\$4 or correspondence\$1 or likelihood)	USPAT	2005/08/18 16:26	

	Type	L #	Hits	Search Text	DBs	Time Stamp	Comments
26	BRS	L29	17	28 same (position\$3 or location\$1)	USPAT	2005/08/18 16:26	
27	BRS	L30	4	29 same (mov\$6 or motion)	USPAT	2005/08/18 16:28	
28	BRS	L31	0	vector\$1 same position\$3 same (sequen\$6 near\$3 pose) same motion	USPAT	2005/08/18 16:29	
29	IS&R	L32	4305	(382/103,149,151,159,181,190,199,203,209,216,218,219,291).CCLS.	USPAT	2005/08/18 16:29	
30	IS&R	L33	334	(348/135).CCLS.	USPAT	2005/08/18 16:30	
31	BRS	L34	6	(pose near\$3 (estimat\$4 or approximat\$4 or true or actual or exact or perfect or accurate\$2)) same shape\$1 same (boundar\$3 or edge\$3)	USPAT	2005/08/18 16:33	
32	BRS	L35	289	(pose near\$3 (estimat\$4 or approximat\$4 or true or actual or exact or perfect or accurate\$2))	USPAT	2005/08/18 16:40	
33	BRS	L36	53	32 and 35	USPAT	2005/08/18 16:34	
34	BRS	L37	0	33 and 35	USPAT	2005/08/18 16:35	
35	BRS	L38	6	36 and (motion near\$2 transform\$6)	USPAT	2005/08/18 16:36	

	Type	L #	Hits	Search Text	DBs	Time Stamp	Comments
36	BRS	L39	20106	(table\$1 or lookup or lookup) near10 (boundary\$3 or edge\$3)	USPAT	2005/08/18 16:39	
37	BRS	L40	5	39 same pose	USPAT	2005/08/18 16:40	
38	BRS	L41	708	table\$1 same pose	USPAT	2005/08/18 16:40	
39	BRS	L42	18	41 and (pose near3 (estimate\$4 or approximate\$4 or true or actual or exact or perfect or accurate\$2))	USPAT	2005/08/18 16:40	
40	BRS	L43	8	32 and 42	USPAT	2005/08/18 16:41	